Dynamics of adhesive particles and optimal transportation of mass

Gershon Wolansky

Department of Mathematics, Technion 32000 Haifa, ISRAEL

E-mail: gershonw@math.technion.ac.il

- 2

イロン イヨン イヨン イヨン



#### • Fragmentation and Coagulation

A B F A B F

3

- Fragmentation and Coagulation
- Zero-pressure gas dynamics and shock waves as models of coagulations

3

A B < A B </p>

- Fragmentation and Coagulation
- Zero-pressure gas dynamics and shock waves as models of coagulations
- Reversible dynamics and action principle

- Fragmentation and Coagulation
- Zero-pressure gas dynamics and shock waves as models of coagulations
- Reversible dynamics and action principle
- Implementation of reversible dynamics:

- Fragmentation and Coagulation
- Zero-pressure gas dynamics and shock waves as models of coagulations
- Reversible dynamics and action principle
- Implementation of reversible dynamics:

(I) Inner energy

- Fragmentation and Coagulation
- Zero-pressure gas dynamics and shock waves as models of coagulations
- Reversible dynamics and action principle
- Implementation of reversible dynamics:
  - (I) Inner energy(II) Extended Lagrangian systems

**Coagulation Kernel:** 

3

<ロ> (日) (日) (日) (日) (日)

**Coagulation Kernel:** 

 $K_c(n,m):m,n \Longrightarrow m+n$ 

3

- 4 同 ト 4 三 ト 4 三 ト

**Coagulation Kernel:** 

 $K_c(n,m): m,n \Longrightarrow m+n$ 

**Fragmentation Kernel:** 

 $K_f(n,m): n \Longrightarrow n-m, m$ 

• • = • • = •

3

**Coagulation Kernel:** 

 $K_c(n,m):m,n \Longrightarrow m+n$ 

**Fragmentation Kernel:** 

 $K_f(n,m): n \Longrightarrow n-m,m$ 

Density of clusters of size *n* is given by f(n, t). The evolution equation:

$$\frac{\partial f(n,t)}{\partial t} = \int_0^n K_c(n-m,m)f(m,t)dm - f(n,t)\int_n^\infty K_c(n,m)dm + \int_0^\infty K_f(n+m,m)f(m+n,t)dm - f(n,t)\int_0^n K_f(n,m)dm \quad (1)$$

向下 イヨト イヨト ニヨ

Consider a swarm of N particles of masses  $m_i$  whose orbits are given by  $x_i(t)$ . The initial (at t = 0) positions and velocities of the particles are prescribed

$$x_i(0) := x_i^{(0)}$$
;  $\dot{x}_i(0) = v_i^{(0)}$ .

If there are no external forces, then, at least until two (or more) particles collide, the orbits of the particles are given by

$$x_i(t) = x_i^{(0)} + t v_i^{(0)}$$

In the limit

$$\rho(x,0) = \lim_{N \to \infty} N^{-1} \sum_{i}^{N} m_i \delta_{x_i^{(0)}}$$
$$(\rho \vec{u}) (x,0) = \lim_{N \to \infty} N^{-1} \sum_{i}^{N} m_i v_i^{(0)} \delta_{x_i^{(0)}} ,$$

the density and velocity fields satisfies, formally, the system of conservation law (*zero-pressure dynamics*)

$$rac{\partial 
ho}{\partial t} + 
abla_{ imes} \cdot (
ho ec u) = 0 \quad ; \quad rac{\partial (
ho ec u)}{\partial t} + 
abla_{ imes} \cdot (
ho ec u \otimes ec u) = 0 \; .$$

This system can be viewed as an initial value problem, subjected to

 $\rho(x,0) = \rho_0(x) \ge 0 \quad , \quad \vec{u}(x,0) = \vec{u}_0(x) \ .$ 

As long as the solution is *classical* (namely, continuously differentiable), the momentum equation can be written as the Burger's equation

 $\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla_{\mathsf{x}} \vec{u} = 0 \; .$ 

This system can be viewed as an initial value problem, subjected to

 $\rho(x,0) = \rho_0(x) \ge 0 \quad , \quad \vec{u}(x,0) = \vec{u}_0(x) \ .$ 

As long as the solution is *classical* (namely, continuously differentiable), the momentum equation can be written as the Burger's equation

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla_{\mathsf{x}} \vec{u} = 0 \; .$$

Zero pressure and dynamics of adhesive particles

- Zeldovich (1970): Sticky particle model.
- Existence: E, Rykov and Sinai (1996) Brenier and Grenier (1998), ect.
- Uniqueness: Bouchut and James (1999)

Gershon Wolansky (Technion)

3

• Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)

- Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)
- Energy is lost in the inelastic collision. Hence, the sticking particle dynamics is not reversible.

- Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)
- Energy is lost in the inelastic collision. Hence, the sticking particle dynamics is not reversible.
- As a result, the solutions of the zero-pressure gas dynamics corresponding to sticking particle are (generalized) entropy solutions: (no refractive shocks, no spontaneous emergence of refractive waves).

- Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)
- Energy is lost in the inelastic collision. Hence, the sticking particle dynamics is not reversible.
- As a result, the solutions of the zero-pressure gas dynamics corresponding to sticking particle are (generalized) entropy solutions: (no refractive shocks, no spontaneous emergence of refractive waves).
- Hence, there are no fragmentation waves!

- Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)
- Energy is lost in the inelastic collision. Hence, the sticking particle dynamics is not reversible.
- As a result, the solutions of the zero-pressure gas dynamics corresponding to sticking particle are (generalized) entropy solutions: (no refractive shocks, no spontaneous emergence of refractive waves).
- Hence, there are no fragmentation waves!
- The process of fragmentation is currently described by phenomenological kernels. It is based on ad hoc probabilistic assumptions which have nothing to do with the fundamental principle of physics!

通 ト イヨト イヨト

- Fundamental principles of physics are time reversible. (It is us, the observers, who are, unfortunately, not reversible!)
- Energy is lost in the inelastic collision. Hence, the sticking particle dynamics is not reversible.
- As a result, the solutions of the zero-pressure gas dynamics corresponding to sticking particle are (generalized) entropy solutions: (no refractive shocks, no spontaneous emergence of refractive waves).
- Hence, there are no fragmentation waves!
- The process of fragmentation is currently described by phenomenological kernels. It is based on ad hoc probabilistic assumptions which have nothing to do with the fundamental principle of physics!
- In physics, reversible processes are usually derived from an action principle.

## The action principle of a free dynamics For an orbit $\vec{x}(t) = (x_1(t), \dots x_N(t)) \ 0 \le t \le T$ , the action is

3

- 4 同 6 4 日 6 4 日 6

# The action principle of a free dynamics For an orbit $\vec{x}(t) = (x_1(t), \dots, x_N(t)) \ 0 \le t \le T$ , the action is $A(\vec{x}; T) := \int_0^T L(m_1 \dot{x}_1, \dots, m_N \dot{x}_N) dt$

where

$$L(p_1,\ldots p_N):=\sum_1^N \frac{|p_i|^2}{2m_i}$$

and

$$\underline{A}(\vec{x}^{(0)}, \vec{x}^{(1)}; T) :=$$

$$\min_{\vec{x}(\cdot)} \left\{ A(\vec{x}; T) ; \ \vec{x}(0) = \vec{x}^{(0)} , \vec{x}(T) = \vec{x}^{(1)} \right\}$$

Note that here the masses  $m_i$  of the particles are constants.

# The action principle of a free dynamics For an orbit $\vec{x}(t) = (x_1(t), \dots x_N(t)) \ 0 \le t \le T$ , the action is $A(\vec{x}; T) := \int_0^T L(m_1 \dot{x}_1, \dots m_N \dot{x}_N) dt$

where

$$L(p_1,\ldots p_N):=\sum_1^N \frac{|p_i|^2}{2m_i}$$

and

$$\underline{A}(\vec{x}^{(0)}, \vec{x}^{(1)}; T) :=$$

$$\min_{\vec{x}(\cdot)} \left\{ A(\vec{x}; T) ; \ \vec{x}(0) = \vec{x}^{(0)} , \vec{x}(T) = \vec{x}^{(1)} \right\} .$$

Note that here the masses  $m_i$  of the particles are constants.

In order to implement collisions into an action principle, we must introduce inner energy, and allow particles to exchange mass  $\rightarrow e^{2} \rightarrow e^$ 

Gershon Wolansky (Technion)

Quasi-rigid deformations

State space:  $\Gamma$  is the set of N orbits  $(x_i(t), m_i(t))$  so that

3

State space:  $\Gamma$  is the set of N orbits  $(x_i(t), m_i(t))$  so that a)  $x_i \in C([0, T]; \Omega), 1 \le i \le N.$ 

3

A B A A B A

State space:  $\Gamma$  is the set of N orbits  $(x_i(t), m_i(t))$  so that

a)  $x_i \in C([0, T]; \Omega), 1 \le i \le N.$ 

b)  $m_i$  are sequentially constants, so  $dm_i/dt = 0$  if  $x_i(t) \neq x_j(t)$  for any  $i \neq j$ .

A B K A B K

State space:  $\Gamma$  is the set of N orbits  $(x_i(t), m_i(t))$  so that

a)  $x_i \in C([0, T]; \Omega), 1 \le i \le N.$ 

b)  $m_i$  are sequentially constants, so  $dm_i/dt = 0$  if  $x_i(t) \neq x_j(t)$  for any  $i \neq j$ .

c) If for  $\tau \in (0, T)$  there exists a subset  $I \subset \{1, ..., N\}$  for which  $x_i(\tau) = x_j(\tau) \equiv x$  for all  $i, j \in I$  while  $x_l(\tau) \neq x$  for  $l \notin I$ , then

$$\sum_{i\in I}m_i(t^-)=\sum_{i\in I}m_i(t^+).$$

8 / 26

#### Inner energy

There is a function  $\xi = \xi(m)$ , called the inner energy of a particle of mass m, such that

$$egin{array}{lll} \xi\in {\mathcal C}({\mathbb R}^+) &, \ \xi(0)=0, & orall m_1,m_2>0 \ \Longrightarrow \xi(m_1)+\xi(m_2)<\xi(m_1+m_2) \ . \end{array}$$

Note that it is satisfied by any convex function on  $\mathbb{R}^+$  for which  $\xi(0) = 0$ .

3

- 4 同 6 4 日 6 4 日 6

#### Inner energy

There is a function  $\xi = \xi(m)$ , called the inner energy of a particle of mass m, such that

 $\xi \in C(\mathbb{R}^+)$ ,  $\xi(0) = 0$ ,  $\forall m_1, m_2 > 0$  $\implies \xi(m_1) + \xi(m_2) < \xi(m_1 + m_2)$ .

Note that it is satisfied by any convex function on  $\mathbb{R}^+$  for which  $\xi(0) = 0$ . For example:

 $\xi(m) = -m^{\sigma} ext{ if } 0 < \sigma < 1 ext{ , or } \xi(m) = m^{\sigma} ext{ if } \sigma > 1 ext{ .}$ 

- 3

• • = • • = •

#### Inner energy

There is a function  $\xi = \xi(m)$ , called the inner energy of a particle of mass m, such that

 $\xi \in C(\mathbb{R}^+)$ ,  $\xi(0) = 0$ ,  $\forall m_1, m_2 > 0$  $\implies \xi(m_1) + \xi(m_2) < \xi(m_1 + m_2)$ .

Note that it is satisfied by any convex function on  $\mathbb{R}^+$  for which  $\xi(0) = 0$ . For example:

 $\xi(m) = -m^{\sigma}$  if  $0 < \sigma < 1$  , or  $\xi(m) = m^{\sigma}$  if  $\sigma > 1$  .

The dynamics of this system is obtained by the action:  $A : \Gamma \to \mathbb{R}$  defined for  $\gamma := (x_1, m_1 \dots x_N, m_M)$  by

$$A(\gamma; T) := \sum_{1}^{N} \int_{0}^{T} \left[ \frac{1}{2} m_{i}(t) |\dot{x}_{i}|^{2} - \xi(m_{i}(t)) \right] dt$$

- 本語 医 本 医 医 一 医

#### Theorem

If  $\gamma$  is a minimizer of the action A within the set  $\Gamma$  subjected to the end conditions  $\gamma(0) = \left(x_1^{(0)}, m_1^{(0)} \dots x_N^{(0)}, m_N^{(0)}\right)$ ,  $\gamma(T) = \left(x_1^{(T)}, m_1^{(T)} \dots x_N^{(T)}, m_N^{(T)}\right)$ , then  $\gamma$  preserves both the linear momentum

$$\mathbf{P} := \sum_{1}^{N} m_i(t) \dot{x}_i(t)$$

and energy

$$\mathbf{E} := rac{1}{2} \sum_{1}^{N} m_i(t) \, |\dot{x}_i(t)|^2 + \sum_{1}^{N} \xi(m_i(t)) \; .$$

## Extended Lagrangian formulation

Assume that the distribution of particles at time t is given by a positive measure  $\mu_{(t)}$  on  $\Omega$ . We usually denote a trajectory of probability measures  $\mu_{(t)}$ ,  $0 \le t \le T$  by  $\mu$ . We denote the set  $\mathbf{H}_2[0, T]$  as all such trajectories for which

$$\begin{split} \|\mu\|_{2,T}^{2} &:= \inf_{\vec{E}} \int_{0}^{T} \left| \frac{d\vec{E}_{(t)}}{d\mu_{(t)}} \right|^{2} \mu_{(t)}(dx) dt < \infty \\ &\frac{\partial \mu}{\partial t} + \nabla_{x} \cdot \vec{E}_{(t)} = 0 \end{split}$$

in the sense of distributions.

## Extended Lagrangian formulation

Assume that the distribution of particles at time t is given by a positive measure  $\mu_{(t)}$  on  $\Omega$ . We usually denote a trajectory of probability measures  $\mu_{(t)}$ ,  $0 \le t \le T$  by  $\mu$ . We denote the set  $\mathbf{H}_2[0, T]$  as all such trajectories for which

$$\|\mu\|_{2,T}^{2} := \inf_{\vec{E}} \int_{0}^{T} \left| \frac{d\vec{E}_{(t)}}{d\mu_{(t)}} \right|^{2} \mu_{(t)}(dx) dt < \infty$$
$$\frac{\partial \mu}{\partial t} + \nabla_{x} \cdot \vec{E}_{(t)} = 0$$

in the sense of distributions. For a given pair of probability measures  $\mu_0, \mu_1$ , the extended action principle is defined by

$$\underline{A}(\mu_0,\mu_1) := \min_{\mu} \frac{1}{2} \|\mu\|_{2,T}^2$$

$$\mu_{(0)} = \mu_0, \ \mu_{(T)} = \mu_1$$
.

The minimization problem is a special case of McCann interpolation

$$\mu_{(t)} = \left[\frac{T-t}{T}\mathsf{Id} + \frac{t}{T}\mathsf{S}\right]_{\#}\mu_{0}$$

where **S** is the map which realizes the optimal transportation of  $\mu_0$  to  $\mu_1$  under quadratic cost:

$$\inf_{\mathbf{S}_{\#}\mu_{0}=\mu_{1}}\int_{\Omega}|x-\mathbf{S}(x)|^{2}\,\mu_{0}(dx)$$

過 ト イヨ ト イヨト
The minimization problem is a special case of McCann interpolation

$$\mu_{(t)} = \left[\frac{T-t}{T}\mathsf{Id} + \frac{t}{T}\mathsf{S}\right]_{\#}\mu_{0}$$

where **S** is the map which realizes the optimal transportation of  $\mu_0$  to  $\mu_1$  under quadratic cost:

$$\inf_{\mathbf{S}_{\#}\mu_{0}=\mu_{1}}\int_{\Omega}|x-\mathbf{S}(x)|^{2}\,\mu_{0}(dx)$$

In case of discrete measure (D) The "Graph orbit"  $\Gamma$  is a special case of admissible  $\mu$ :

$$\mu = \sum_{1}^{N} m_i(t) \delta_{x_i(t)}$$

$$\inf_{\Lambda} \sum_{1}^{N} \sum_{1}^{N} \Lambda_{i,j} |x_i - y_j|^2 ,$$

where  $\sum_{i} \Lambda_{i,j} = m_j(T), \ \sum_{j} \Lambda_{i,j} = m_i(0).$ 

## Extended action subjected to a prescribed pressure

The extended Lagrangian with a pressure

$$A_P(\mu) = \frac{1}{2} \|\mu\|_2^2 - \int_0^T P(x,t) \mu_{(t)}(dx) dt \; .$$

The associated Hamilton-Jacobi equation

$$rac{\partial \phi}{\partial t} + rac{1}{2} |
abla_x \phi|^2 + P = 0 \quad ; \quad (x,t) \in \Omega imes (0,T) \; ,$$

and the continuity equation

$$\frac{\partial \mu_{(t)}}{\partial t} + \nabla_{\mathsf{x}} \cdot \left( \mu_{(t)} \nabla_{\mathsf{x}} \phi \right) = \mathbf{0} \; .$$

The end conditions:

$$\mu_{(0)} = \mu_0$$
 ;  $\mu_{(T)} = \mu_1$ .

# Extended action subjected to a prescribed pressure

The extended Lagrangian with a pressure

$$A_P(\mu) = \frac{1}{2} \|\mu\|_2^2 - \int_0^T P(x,t) \mu_{(t)}(dx) dt \; .$$

The associated Hamilton-Jacobi equation

$$rac{\partial \phi}{\partial t} + rac{1}{2} |
abla_x \phi|^2 + P = 0 \quad ; \quad (x,t) \in \Omega imes (0,T) \; ,$$

and the continuity equation

$$\frac{\partial \mu_{(t)}}{\partial t} + \nabla_{\mathsf{x}} \cdot \left( \mu_{(t)} \nabla_{\mathsf{x}} \phi \right) = \mathbf{0} \; .$$

The end conditions:

$$\mu_{(0)} = \mu_0$$
 ;  $\mu_{(T)} = \mu_1$ .

#### Theorem

For any pair of end conditions  $\mu_0, \mu_1$  there exists an orbit  $\mu \in H_2([0, T])$  which realizes the infimum of  $A_P$ .

Gershon Wolansky (Technion)

Quasi-rigid deformations

13 / 26

The cost function:

$$C_{P}(x, y, \tau, t) := \min\left\{\int_{\tau}^{t} \left(\frac{|\bar{x}|^{2}}{2} + P(\bar{x}(s), s)\right) ds \quad ; \quad \bar{x} : [\tau, t] \to \Omega\right\}$$
(2)

where  $\overline{x}(\tau) = y$ ,  $\overline{x}(t) = x$ .

The cost function:

$$C_{P}(x, y, \tau, t) := \min\left\{\int_{\tau}^{t} \left(\frac{|\overline{x}|^{2}}{2} + P(\overline{x}(s), s)\right) ds \quad ; \quad \overline{x} : [\tau, t] \to \Omega\right\}$$
(2)

where  $\overline{x}(\tau) = y$ ,  $\overline{x}(t) = x$ . In particular, if P = 0:

$$C_0(x,y, au,t) := rac{|x-y|^2}{2(t- au)} \; .$$

Gershon Wolansky (Technion)

3

伺下 イヨト イヨト

Gershon Wolansky (Technion)

3

イロト イヨト イヨト イヨト

i) A forward (res. backward) solution is defined, for  $t \in [0, T]$ , by  $\overline{\phi}(x, t) := \min_{y} \{C_{P}(y, x, 0, t) + \phi(y, 0)\}$ , res.  $\underline{\phi}(x, t) := \sup_{y} \{-C_{P}(x, y, t, T) + \phi(y, T)\}.$ 

3

• • = • • = •

i) A forward (res. backward) solution is defined, for  $t \in [0, T]$ , by  $\overline{\phi}(x, t) := \min_{y} \{C_{P}(y, x, 0, t) + \phi(y, 0)\}$ , res.  $\underline{\phi}(x, t) := \sup_{y} \{-C_{P}(x, y, t, T) + \phi(y, T)\}.$ ii) If  $\phi(\cdot, 0)$  and  $\phi(\cdot, T)$  are Lipschitz on  $\Omega$  then both  $\overline{\phi}$  and  $\phi$  are Lipschitz on  $\Omega \times [0, T].$ 

i) A forward (res. backward) solution is defined, for  $t \in [0, T]$ , by  $\overline{\phi}(x, t) := \min_{y} \{ C_{P}(y, x, 0, t) + \phi(y, 0) \}$ , res.  $\underline{\phi}(x, t) := \sup_{y} \{ -C_{P}(x, y, t, T) + \phi(y, T) \}.$ 

ii) If  $\phi(\cdot, 0)$  and  $\phi(\cdot, T)$  are Lipschitz on  $\Omega$  then both  $\overline{\phi}$  and  $\underline{\phi}$  are Lipschitz on  $\Omega \times [0, T]$ .

iii)  $(\overline{\phi}, \underline{\phi})$  is called a reversible pair if  $\overline{\phi} = \underline{\phi}$  on  $\Omega$  for t = 0and t = T. In this case,  $\overline{\phi}(x, t) \ge \underline{\phi}(x, t)$  on  $\Omega \times [0, T]$ .

i) A forward (res. backward) solution is defined, for  $t \in [0, T]$ , by  $\overline{\phi}(x, t) := \min_{y} \{C_{P}(y, x, 0, t) + \phi(y, 0)\}$ , res.  $\underline{\phi}(x, t) := \sup_{y} \{-C_{P}(x, y, t, T) + \phi(y, T)\}.$ 

ii) If  $\phi(\cdot, 0)$  and  $\phi(\cdot, T)$  are Lipschitz on  $\Omega$  then both  $\overline{\phi}$  and  $\underline{\phi}$  are Lipschitz on  $\Omega \times [0, T]$ .

iii)  $(\overline{\phi}, \underline{\phi})$  is called a reversible pair if  $\overline{\phi} = \underline{\phi}$  on  $\Omega$  for t = 0and t = T. In this case,  $\overline{\phi}(x, t) \ge \underline{\phi}(x, t)$  on  $\Omega \times [0, T]$ . iv) If  $(\overline{\phi}, \overline{\phi})$  is a reversible pair, then the reversibility set is defined by

 $(\overline{\phi}, \underline{\phi})$  is a reversible pair, then the reversibility set is defined by  $\mathcal{K}_0(\overline{\phi}, \underline{\phi}) := \{(x, t) \in \Omega \times (0, T) ; \overline{\phi}(x, t) = \underline{\phi}(x, t) := \psi(x, t)\}$   $\nabla_x \psi(x, t) = \nabla_x \overline{\phi} = \nabla_x \underline{\phi}$  is Lipschitz on the reversibility set. We call  $\psi$  a reversible solution.

If  $\phi_0, \phi_1$  maximizes  $\int_{\Omega} (\phi_1 \mu_1(dx) - \phi_0 \mu_0(dx))$  subjected  $\phi_1(x) - \phi_0(y) \leq C_P(x, y, 0, T)$  for any  $x, y \in \Omega$ , then  $\{\phi_0, \phi_1\}$  is a reversible pair. The reversibility function  $\psi$  verifies the Hamilton-Jacobi equation, and the optimal solution of  $A_P$  is supported in  $K_0(\phi_0, \phi_1)$  and verifies the continuity equation subjected  $\nabla \phi = \nabla \psi$ . Moreover, the flow

$$\frac{d\mathbf{S}^{(t,s)}}{dt} = \nabla\psi\left(\mathbf{S}_{(x)}^{(t)}, t\right) \quad ; \quad \mathbf{T}^{(t,t)} := \mathbf{I}_{\mathbf{d}}$$

transports this orbit  $S_{\#}^{(t,s)}\mu_{(s)} = \mu_{(t)}$ .

(本間) (本語) (本語) (二語)

If  $\phi_0, \phi_1$  maximizes  $\int_{\Omega} (\phi_1 \mu_1(dx) - \phi_0 \mu_0(dx))$  subjected  $\phi_1(x) - \phi_0(y) \leq C_P(x, y, 0, T)$  for any  $x, y \in \Omega$ , then  $\{\phi_0, \phi_1\}$  is a reversible pair. The reversibility function  $\psi$  verifies the Hamilton-Jacobi equation, and the optimal solution of  $A_P$  is supported in  $K_0(\phi_0, \phi_1)$  and verifies the continuity equation subjected  $\nabla \phi = \nabla \psi$ . Moreover, the flow

$$\frac{d\mathbf{S}^{(t,s)}}{dt} = \nabla\psi\left(\mathbf{S}_{(x)}^{(t)}, t\right) \quad ; \quad \mathbf{T}^{(t,t)} := \mathbf{I}_{\mathbf{d}}$$

transports this orbit  $\mathbf{S}_{\#}^{(\mathbf{t},\mathbf{s})}\mu_{(\mathbf{s})} = \mu_{(\mathbf{t})}$ .

• The particles of the optimal flow subjected to a prescribed pressure do not collide (and, in particular, do not stick).

イロト 不得下 イヨト イヨト 二日

If  $\phi_0, \phi_1$  maximizes  $\int_{\Omega} (\phi_1 \mu_1(dx) - \phi_0 \mu_0(dx))$  subjected  $\phi_1(x) - \phi_0(y) \leq C_P(x, y, 0, T)$  for any  $x, y \in \Omega$ , then  $\{\phi_0, \phi_1\}$  is a reversible pair. The reversibility function  $\psi$  verifies the Hamilton-Jacobi equation, and the optimal solution of  $A_P$  is supported in  $K_0(\phi_0, \phi_1)$  and verifies the continuity equation subjected  $\nabla \phi = \nabla \psi$ . Moreover, the flow

$$\frac{d\mathbf{S}^{(t,s)}}{dt} = \nabla\psi\left(\mathbf{S}_{(x)}^{(t)}, t\right) \quad ; \quad \mathbf{T}^{(t,t)} := \mathbf{I}_{\mathbf{d}}$$

transports this orbit  $S_{\#}^{(t,s)}\mu_{(s)} = \mu_{(t)}$ .

- The particles of the optimal flow subjected to a prescribed pressure do not collide (and, in particular, do not stick).
- There are no shock waves for the Hamilton-Jacobi equation. Indeed,  $\psi$  is a reversible solution, as claimed.

イロト 不得下 イヨト イヨト 二日

We now wish to extend the action principle to orbits composed of (Borel) measures in  $\Omega$ . Let  $\overline{\mathcal{M}}$  be the set of such probability Borel measures. For any  $\mu \in \overline{\mathcal{M}}$  set  $\mu = \mu^{pp} + \tilde{\mu}$  to be its *unique* decomposition into its atomic and non-atomic parts. For each  $\mu \in \overline{\mathcal{M}}$  we define the inner energy  $\Xi(\mu)$  as

$$\Xi(\mu) := \Xi(\mu^{pp}) = \sum_{x; \mu(\{x\}) > 0} \xi(\mu(\{x\})) \; .$$

We now wish to extend the action principle to orbits composed of (Borel) measures in  $\Omega$ . Let  $\overline{\mathcal{M}}$  be the set of such probability Borel measures. For any  $\mu \in \overline{\mathcal{M}}$  set  $\mu = \mu^{pp} + \tilde{\mu}$  to be its *unique* decomposition into its atomic and non-atomic parts. For each  $\mu \in \overline{\mathcal{M}}$  we define the inner energy  $\Xi(\mu)$  as

$$\Xi(\mu) := \Xi(\mu^{pp}) = \sum_{x; \mu(\{x\}) > 0} \xi(\mu(\{x\})) \; .$$

For any  $\mu \in H_2([0, T])$  define the action as:

$$\mathcal{A}_{\Xi}(\mu;T) := rac{1}{2} \|\mu\|_{2,T}^2 - \int_0^T \Xi(\mu_{(t)}) dt \; .$$

We now wish to extend the action principle to orbits composed of (Borel) measures in  $\Omega$ . Let  $\overline{\mathcal{M}}$  be the set of such probability Borel measures. For any  $\mu \in \overline{\mathcal{M}}$  set  $\mu = \mu^{pp} + \tilde{\mu}$  to be its *unique* decomposition into its atomic and non-atomic parts. For each  $\mu \in \overline{\mathcal{M}}$  we define the inner energy  $\Xi(\mu)$  as

$$\Xi(\mu) := \Xi(\mu^{pp}) = \sum_{x; \mu(\{x\}) > 0} \xi(\mu(\{x\})) \; .$$

For any  $\mu \in H_2([0, T])$  define the action as:

$$\mathcal{A}_{\Xi}(\mu;T) := rac{1}{2} \|\mu\|_{2,T}^2 - \int_0^T \Xi(\mu_{(t)}) dt \; .$$

We now pose the following assumptions on  $\xi$ :

$$\xi: \mathbb{R}^+ \to \mathbb{R}^+ , \quad \lim_{m \to 0} \frac{\xi(m)}{m} = 0$$

We now wish to extend the action principle to orbits composed of (Borel) measures in  $\Omega$ . Let  $\overline{\mathcal{M}}$  be the set of such probability Borel measures. For any  $\mu \in \overline{\mathcal{M}}$  set  $\mu = \mu^{pp} + \tilde{\mu}$  to be its *unique* decomposition into its atomic and non-atomic parts. For each  $\mu \in \overline{\mathcal{M}}$  we define the inner energy  $\Xi(\mu)$  as

$$\Xi(\mu) := \Xi(\mu^{pp}) = \sum_{x; \mu(\{x\}) > 0} \xi(\mu(\{x\})) .$$

For any  $\mu \in H_2([0, T])$  define the action as:

$$\mathcal{A}_{\Xi}(\mu;T) := rac{1}{2} \|\mu\|_{2,T}^2 - \int_0^T \Xi(\mu_{(t)}) dt \; .$$

We now pose the following assumptions on  $\xi$ :

$$\xi: \mathbb{R}^+ \to \mathbb{R}^+$$
,  $\lim_{m \to 0} \frac{\xi(m)}{m} = 0$ 

**Remark**: The assumption  $\xi(m) = m^{\sigma}$  for  $\sigma > 1$  verifies verifies this condition.

Gershon Wolansky (Technion)

17 / 26

#### Lemma

The action  $A_{\Xi}(\cdot, T)$  is lower-semi-continues (l.s.c) with respect to  $C([0, T]; C^*(\Omega))$ .

3

伺い イヨト イヨト

#### Lemma

The action  $A_{\Xi}(\cdot, T)$  is lower-semi-continues (l.s.c) with respect to  $C([0, T]; C^*(\Omega))$ .

#### Theorem

Given  $\mu_0, \mu_1 \in \overline{\mathcal{M}}$ , there exists an action minimizer  $\mu \in \mathbf{H}_2[0, T]$  for  $\underline{A}(\mu_0, \mu_1; T) := \min_{\mu} A_{\Xi}(\mu, T)$ 

subjected to  $\mu_{(0)}=\mu_0$  ,  $\mu_{(\mathcal{T})}=\mu_1$ 

We first consider a relaxation of the inner energy functional as follows:

3

A D A D A D A

We first consider a relaxation of the inner energy functional as follows:

### Definition

Let  $J : \mathbb{R}^+ \to \mathbb{R}^+$  be a convex function satisfying J(0) = J'(0) = 0. Let  $\theta \in C_0^{\infty}(\Omega; \mathbb{R}^+)$  such that  $\theta(0) = 1 \ge \theta(x)$  for all  $x \in \Omega$ . For each  $\epsilon > 0$ , the inner energy function  $\xi$  corresponding to J is defined by

$$\xi(m):=\int_\Omega J(m heta(x))dx$$
 ;  $m\geq 0$  .

過 ト イヨ ト イヨト

We first consider a relaxation of the inner energy functional as follows:

### Definition

Let  $J : \mathbb{R}^+ \to \mathbb{R}^+$  be a convex function satisfying J(0) = J'(0) = 0. Let  $\theta \in C_0^{\infty}(\Omega; \mathbb{R}^+)$  such that  $\theta(0) = 1 \ge \theta(x)$  for all  $x \in \Omega$ . For each  $\epsilon > 0$ , the inner energy function  $\xi$  corresponding to J is defined by

$$\xi(m):=\int_\Omega J(m heta(x))dx$$
 ;  $m\geq 0$  .

Let  $\theta_{\epsilon}(x) := \theta(x/\epsilon)$  and

$$\Xi_{\epsilon}(\mu) := \epsilon^{-1} \int_{\Omega} J\left(\int_{\Omega} heta_{\epsilon}(x-y)\mu(dx)
ight) dy \; .$$

通 と く ヨ と く ヨ と

We first consider a relaxation of the inner energy functional as follows:

### Definition

Let  $J : \mathbb{R}^+ \to \mathbb{R}^+$  be a convex function satisfying J(0) = J'(0) = 0. Let  $\theta \in C_0^{\infty}(\Omega; \mathbb{R}^+)$  such that  $\theta(0) = 1 \ge \theta(x)$  for all  $x \in \Omega$ . For each  $\epsilon > 0$ , the inner energy function  $\xi$  corresponding to J is defined by

$$\xi(m):=\int_\Omega J(m heta(x))dx$$
 ;  $m\geq 0$  .

Let  $\theta_{\epsilon}(x) := \theta(x/\epsilon)$  and

$$\Xi_{\epsilon}(\mu) := \epsilon^{-1} \int_{\Omega} J\left(\int_{\Omega} heta_{\epsilon}(x-y)\mu(dx)
ight) dy \; .$$

#### Lemma

For each  $\epsilon > 0$ ,  $\mu \to -\int_0^T \Xi_{\epsilon} (\mu_{(t)}) dt$  is continuous in the weak topology of  $\mathbf{H}_2[0, T]$ .

Gershon Wolansky (Technion)

Let now

$$egin{aligned} &\mathcal{A}^\epsilon_{\Xi}(\mu;\,\mathcal{T}) = rac{1}{2} \|\mu\|^2_{2,\,\mathcal{T}} - \int_0^{\mathcal{T}} \Xi_\epsilon\left(\mu_{(t)}
ight) \, dt \; . \end{aligned}$$

3

< ロ > < 圖 > < 画 > < 画 > <

Let now

$$\mathcal{A}^{\epsilon}_{\Xi}(\mu;T) = rac{1}{2} \|\mu\|^2_{2,T} - \int_0^T \Xi_{\epsilon}\left(\mu_{(t)}
ight) dt \; .$$

### Theorem

Given  $\mu_0, \mu_1 \in \overline{\mathcal{M}}$ , there exists an action minimizer for  $\underline{A}_{\Xi}^{\epsilon}(\mu_0, \mu_1; T) := \min_{\mu} A_{\Xi}^{\epsilon}(\mu; T)$ 

3

伺下 イヨト イヨト

Let now

$$\mathcal{A}^\epsilon_{\Xi}(\mu;T) = rac{1}{2} \|\mu\|^2_{2,T} - \int_0^T \Xi_\epsilon\left(\mu_{(t)}
ight) dt \; .$$

### Theorem

Given  $\mu_0, \mu_1 \in \overline{\mathcal{M}}$ , there exists an action minimizer for

$$\underline{A}_{\underline{\Xi}}^{\epsilon}(\mu_0,\mu_1;T) := \min_{\mu} A_{\underline{\Xi}}^{\epsilon}(\mu;T)$$

Let  $\mu_{\epsilon}$  a minimizer of  $A_{\Xi}^{\epsilon}$ . Since the set  $\mu_{\epsilon}$ ,  $0 < \epsilon < 1$ , is pre-compact in  $H_2[0, T]$ , we can look for a limit point of a subsequence of  $\mu_{\epsilon}$  as  $\epsilon \to 0$ 

Consider now the pair of equations

$$rac{\partial \mu}{\partial t} + 
abla \cdot (\mu 
abla_x \psi) = 0$$
  
 $rac{\partial \psi}{\partial t} + rac{1}{2} |
abla_x \psi|^2 - P_\epsilon = 0 ,$ 

where

$$P_{\epsilon}(x,t) = -\Xi'_{\epsilon}(\mu_{(t)})_{(x,t)} := \epsilon^{-1} \int_{\Omega} J'\left(\int_{\Omega} \theta_{\epsilon}(z-y)\mu_{(t)}(dz)\right) \theta_{\epsilon}(x-y)dy .$$
(3)

**A** ►

Consider now the pair of equations

$$\frac{\partial \mu}{\partial t} + \nabla \cdot (\mu \nabla_x \psi) = 0$$
$$\frac{\partial \psi}{\partial t} + \frac{1}{2} |\nabla_x \psi|^2 - P_{\epsilon} = 0 ,$$

where

$$P_{\epsilon}(x,t) = -\Xi_{\epsilon}'(\mu_{(t)})_{(x,t)} := \epsilon^{-1} \int_{\Omega} J'\left(\int_{\Omega} \theta_{\epsilon}(z-y)\mu_{(t)}(dz)\right) \theta_{\epsilon}(x-y)dy .$$
(3)

### Example

: if  $\mu = \sum m_i \delta_{x_i}$  then

$$P_{\epsilon}(x,t) \approx J'\left(\sum_{j} m_{j}\theta\left(\frac{x_{j}-x}{\epsilon}\right)\right)$$

Very strong and very short range repelling force!

Gershon Wolansky (Technion)

Quasi-rigid deformations

If  $\overline{\mu}^{(\epsilon)}$  is a maximizer of the action  $A_{\Xi}^{\epsilon}$  then there exists a reversible-pair solution  $(\overline{\phi}^{(\epsilon)}, \underline{\phi})^{(\epsilon)}$ . The reversibility set  $K_0(\overline{\phi}^{(\epsilon)}, \underline{\phi}^{(\epsilon)})$  contains the support of  $\overline{\mu}^{(\epsilon)}$  in  $\Omega \times (0, T)$ . In addition, the reversibility set is invariant under the flow generated by the reversible solution

$$rac{d {f S}_{(\epsilon)}{}^{(s,t)}(x)}{dt} = 
abla \psi^{(\epsilon)} \left( {f S}_{(\epsilon)}^{(s,t)}(x),t 
ight) \; .$$

As  $\epsilon \to 0$ , the particles' orbits  $\mathbf{S}_{(\epsilon)}^{(s,t)}$  converge to a set-valued mapping  $\mathbf{S}^{(s,t)}: \Omega \to \mathcal{B}(\Omega)$  so that  $\lim_{\epsilon \to 0} \mathbf{S}_{(\epsilon)}^{(s,t)}(x) \in \mathbf{S}^{(s,t)}(x)$ .

## Formal evolution equations in 1D

Suppose now an optimal transport is presented by the pair  $\mu, \phi$  where

$$\mu_{(t)}(dx) = \rho(x,t)dx + \sum m_i(t)\delta_{x_i(t)}dx ,$$

$$\int_{\Omega} \rho(x,t)dx + \sum m_i(t) = 1 . \quad (4)$$

where  $x_i(t)$  are smooth trajectories and  $m_i(t) > 0$  are smooth for  $t \in [0, T]$ .

# Formal evolution equations in 1D

Suppose now an optimal transport is presented by the pair  $\mu,\phi$  where

$$\mu_{(t)}(dx) = \rho(x,t)dx + \sum m_i(t)\delta_{x_i(t)}dx ,$$

$$\int_{\Omega} \rho(x,t)dx + \sum m_i(t) = 1 . \quad (4)$$

where  $x_i(t)$  are smooth trajectories and  $m_i(t) > 0$  are smooth for  $t \in [0, T]$ .

The continuity equation takes the form

$$rac{\partial 
ho}{\partial t} + 
abla_{ imes} \cdot (
ho 
abla_{ imes} \psi) + \sum \dot{m}_i(t) \delta_{ imes_i(t)} = 0 \; .$$

and the momentum equation

$$rac{\partial \psi}{\partial t} + rac{1}{2} |
abla_x \psi|^2 + \sum \xi^{'}\left(m_i(t)\right) \mathbf{1}(x_i(t) - x) = 0 \;,$$

where 1(x) = 0 if  $x \neq 0$ , 1(1) = 1.

# Reversible solution in the limit $\epsilon = 0$

The limit action function

$$C(y,x,\tau,t;\mu) := \inf_{\overline{x}} \left\{ \int_{\tau}^{t} \left( \frac{1}{2} |\dot{\overline{x}}(s)|^2 - \sum_{\mu_{(s)}(\{x\}) > 0} \xi'(\mu_{(s)}(\{x\})) \mathbf{1}_{(\overline{x}(s),s)} \right) ds \right\}$$

where the infimum is taken on the set of orbits  $\overline{x} : [\tau, t] \to \Omega$  satisfying  $\overline{x}(\tau) = y, \, \overline{x}(t) = x.$ 

# Reversible solution in the limit $\epsilon = 0$

The limit action function

$$C(y,x,\tau,t;\mu) := \inf_{\overline{x}} \left\{ \int_{\tau}^{t} \left( \frac{1}{2} |\dot{\overline{x}}(s)|^2 - \sum_{\mu_{(s)}(\{x\}) > 0} \xi'(\mu_{(s)}(\{x\})) \mathbf{1}_{(\overline{x}(s),s)} \right) ds \right\}$$

where the infimum is taken on the set of orbits  $\overline{x} : [\tau, t] \to \Omega$  satisfying  $\overline{x}(\tau) = y, \ \overline{x}(t) = x.$ Fragmentation:

$$\psi(x,t) = \inf_{y \in \Omega} \left[ C(y,x,0,t;\mu) + \phi_0(y) \right] \le \overline{\phi}(x,t) := \inf_{y \in \Omega} \left[ \frac{|x-y|^2}{2t} + \phi_0(y) \right]$$
(5)

# Reversible solution in the limit $\epsilon = 0$

The limit action function

$$C(y,x,\tau,t;\mu) := \inf_{\overline{x}} \left\{ \int_{\tau}^{t} \left( \frac{1}{2} |\dot{\overline{x}}(s)|^2 - \sum_{\mu_{(s)}(\{x\}) > 0} \xi'(\mu_{(s)}(\{x\})) \mathbb{1}_{(\overline{x}(s),s)} \right) ds \right\}$$

where the infimum is taken on the set of orbits  $\overline{x} : [\tau, t] \to \Omega$  satisfying  $\overline{x}(\tau) = y, \overline{x}(t) = x$ . Fragmentation:

$$\psi(x,t) = \inf_{y \in \Omega} \left[ C(y,x,0,t;\mu) + \phi_0(y) \right] \le \overline{\phi}(x,t) := \inf_{y \in \Omega} \left[ \frac{|x-y|^2}{2t} + \phi_0(y) \right]$$
(5)

Coagulation:

$$\underline{\phi}(x,t) := \sup_{\substack{y \in \Omega}} \left[ -\frac{|x-y|^2}{2(T-t)} + \phi_1(y) \right] \le \sup_{\substack{y \in \Omega}} \left[ C(x,y,t,T;\mu) + \phi_1(y) \right] = \psi(x,t) \quad (6)$$
Gershon Wolansky (Technion) Quasi-rigid deformations Ben Gurion University, 2007 24 / 26

# Representation of the solution

# Representation of the solution

$$\psi(x,t) = \psi_0(x,t) + \sum_i \alpha_i |x - x_i(t)| \ , \ \psi_0 \in C^1 \ .$$
3

$$\psi(x,t) = \psi_0(x,t) + \sum_i \alpha_i |x - x_i(t)| \ , \ \psi_0 \in C^1$$
  
 $\overline{
ho}_i(t) := rac{1}{2} \left[ 
ho(x_i^-(t),t) + 
ho(x_i^-(t),t) 
ight] \ .$   
 $rac{|lpha_i|^2(t)}{8} - \xi'(m_i(t)) = 0 \ ,$ 

and

Then

3

э

$$\begin{split} \psi(x,t) &= \psi_0(x,t) + \sum_i \alpha_i |x - x_i(t)| \quad , \quad \psi_0 \in C^1 \\ \overline{\rho}_i(t) &:= \frac{1}{2} \left[ \rho(x_i^-(t),t) + \rho(x_i^-(t),t) \right] \quad . \end{split}$$
Then
$$\frac{|\alpha_i|^2(t)}{8} - \xi'(m_i(t)) = 0 \quad , \end{aligned}$$
and
$$\begin{aligned} \text{Coagulation} : \quad \frac{dm_i}{dt} = \overline{\rho}_i(t) \sqrt{8\xi'_i(m_i)} \quad . \end{split}$$

э

•

$$\begin{split} \psi(x,t) &= \psi_0(x,t) + \sum_i \alpha_i |x - x_i(t)| \quad , \quad \psi_0 \in C^1 \ .\\ \overline{\rho}_i(t) &:= \frac{1}{2} \left[ \rho(x_i^-(t),t) + \rho(x_i^-(t),t) \right] \ .\\ \end{split}$$
Then
$$\frac{|\alpha_i|^2(t)}{8} - \xi'(m_i(t)) = 0 \ , \\ \end{split}$$
and
$$\begin{aligned} &\text{Coagulation} : \quad \frac{dm_i}{dt} = \overline{\rho}_i(t) \sqrt{8\xi'_i(m_i)} \ .\\ \end{aligned}$$
Fragmentation : \quad \frac{dm\_i}{dt} = -\overline{\rho}\_i(t) \sqrt{8\xi'\_i(m\_i)} \ , \ . \end{split}

Gershon Wolansky (Technion)

Т

Ben Gurion University, 2007 25 / 26

3

while the particle's orbit satisfies the Rankine-Hugoniot condition:

$$\dot{x}_{i} = \frac{1}{2} \left[ \psi_{x}(x_{i}^{+}(t), t) + \psi_{x}(x_{i}^{-}(t), t) \right]$$
$$:= \frac{\partial}{\partial x} \psi_{0}(x_{i}(t), t) + \sum_{j \neq i} \alpha_{j}(t) \frac{x_{i}(t) - x_{j}(t)}{|x_{i}(t) - x_{j}(t)|} .$$
(7)

3



Figure: A representation of a reversible solution. Bold curves: particle orbits. Bold dots: observers positions at time t. Light curves: the characteristic curves for forward (res. backward) solution in the vicinity of type (I) (res. type (II)) orbit. Dashed light lines: the characteristic curves for forward (res. backward) solution in the vicinity of type (II) (res. type (I)) orbit.



Figure: Same as in Fig. **??**, where the relaxation is emphasized in the magnifying lens.

3

• • = • • = •