# Dynamics of adhesive particles and optimal transportation of mass 

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## Overview

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- Fragmentation and Coagulation


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- Zero-pressure gas dynamics and shock waves as models of coagulations


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(I) Inner energy
(II) Extended Lagrangian systems


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Density of clusters of size $n$ is given by $f(n, t)$. The evolution equation:

$$
\begin{align*}
& \frac{\partial f(n, t)}{\partial t}= \\
& \quad \int_{0}^{n} K_{c}(n-m, m) f(m, t) d m-f(n, t) \int_{n}^{\infty} K_{c}(n, m) d m \\
& \quad+\int_{0}^{\infty} K_{f}(n+m, m) f(m+n, t) d m-f(n, t) \int_{0}^{n} K_{f}(n, m) d m \tag{1}
\end{align*}
$$

Consider a swarm of $N$ particles of masses $m_{i}$ whose orbits are given by $x_{i}(t)$. The initial (at $t=0$ ) positions and velocities of the particles are prescribed

$$
x_{i}(0):=x_{i}^{(0)} ; \quad \dot{x}_{i}(0)=v_{i}^{(0)}
$$

If there are no external forces, then, at least until two (or more) particles collide, the orbits of the particles are given by

$$
x_{i}(t)=x_{i}^{(0)}+t v_{i}^{(0)}
$$

In the limit

$$
\begin{aligned}
\rho(x, 0) & =\lim _{N \rightarrow \infty} N^{-1} \sum^{N} m_{i} \delta_{x_{i}^{(0)}} \\
(\rho \vec{u})(x, 0) & =\lim _{N \rightarrow \infty} N^{-1} \sum^{N} m_{i} v_{i}^{(0)} \delta_{x_{i}^{(0)}}
\end{aligned}
$$

the density and velocity fields satisfies, formally, the system of conservation law (zero-pressure dynamics)

$$
\frac{\partial \rho}{\partial t}+\nabla_{x} \cdot(\rho \vec{u})=0 \quad ; \quad \frac{\partial(\rho \vec{u})}{\partial t}+\nabla_{x} \cdot(\rho \vec{u} \otimes \vec{u})=0
$$

This system can be viewed as an initial value problem, subjected to

$$
\rho(x, 0)=\rho_{0}(x) \geq 0 \quad, \quad \vec{u}(x, 0)=\vec{u}_{0}(x) .
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As long as the solution is classical (namely, continuously differentiable), the momentum equation can be written as the Burger's equation

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## Zero pressure and dynamics of adhesive particles

- Zeldovich (1970): Sticky particle model.
- Existence: E, Rykov and Sinai (1996) Brenier and Grenier (1998), ect.
- Uniqueness: Bouchut and James (1999)


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- Hence, there are no fragmentation waves!
- The process of fragmentation is currently described by phenomenological kernels. It is based on ad hoc probabilistic assumptions which have nothing to do with the fundamental principle of physics!
- In physics, reversible processes are usually derived from an action principle.

The action principle of a free dynamics
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A(\vec{x} ; T):=\int_{0}^{T} L\left(m_{1} \dot{x}_{1}, \ldots m_{N} \dot{x}_{N}\right) d t
$$

where

$$
L\left(p_{1}, \ldots p_{N}\right):=\sum_{1}^{N} \frac{\left|p_{i}\right|^{2}}{2 m_{i}}
$$

and

$$
\begin{gathered}
\underline{A}\left(\vec{x}^{(0)}, \vec{x}^{(1)} ; T\right):= \\
\min _{\vec{x}(\cdot)}\left\{A(\vec{x} ; T) ; \vec{x}(0)=\vec{x}^{(0)}, \vec{x}(T)=\vec{x}^{(1)}\right\} .
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Note that here the masses $m_{i}$ of the particles are constants.

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In order to implement collisions into an action principle, we must introduce inner energy, and allow particles to exchange mass.

## System of finite number of particles

State space: $\Gamma$ is the set of $N$ orbits $\left(x_{i}(t), m_{i}(t)\right)$ so that

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b) $m_{i}$ are sequentially constants, so $d m_{i} / d t=0$ if $x_{i}(t) \neq x_{j}(t)$ for any $i \neq j$.
c) If for $\tau \in(0, T)$ there exists a subset $I \subset\{1, \ldots N\}$ for which $x_{i}(\tau)=x_{j}(\tau) \equiv x$ for all $i, j \in I$ while $x_{l}(\tau) \neq x$ for $I \notin I$, then

$$
\sum_{i \in I} m_{i}\left(t^{-}\right)=\sum_{i \in I} m_{i}\left(t^{+}\right)
$$

## Inner energy

There is a function $\xi=\xi(m)$, called the inner energy of a particle of mass $m$, such that

$$
\begin{gathered}
\xi \in C\left(\mathbb{R}^{+}\right), \xi(0)=0, \quad \forall m_{1}, m_{2}>0 \\
\Longrightarrow \xi\left(m_{1}\right)+\xi\left(m_{2}\right)<\xi\left(m_{1}+m_{2}\right)
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The dynamics of this system is obtained by the action: $A: \Gamma \rightarrow \mathbb{R}$ defined for $\gamma:=\left(x_{1}, m_{1} \ldots x_{N}, m_{M}\right)$ by

$$
A(\gamma ; T):=\sum_{1}^{N} \int_{0}^{T}\left[\frac{1}{2} m_{i}(t)\left|\dot{x}_{i}\right|^{2}-\xi\left(m_{i}(t)\right)\right] d t
$$

## Theorem

If $\gamma$ is a minimizer of the action $A$ within the set $\Gamma$ subjected to the end conditions $\gamma(0)=\left(x_{1}^{(0)}, m_{1}^{(0)} \ldots x_{N}^{(0)}, m_{N}^{(0)}\right)$,
$\gamma(T)=\left(x_{1}^{(T)}, m_{1}^{(T)} \ldots x_{N}^{(T)}, m_{N}^{(T)}\right)$, then $\gamma$ preserves both the linear momentum

$$
\mathbf{P}:=\sum_{1}^{N} m_{i}(t) \dot{x}_{i}(t)
$$

and energy

$$
\mathbf{E}:=\frac{1}{2} \sum_{1}^{N} m_{i}(t)\left|\dot{x}_{i}(t)\right|^{2}+\sum_{1}^{N} \xi\left(m_{i}(t)\right) .
$$

## Extended Lagrangian formulation

Assume that the distribution of particles at time $t$ is given by a positive measure $\mu_{(t)}$ on $\Omega$. We usually denote a trajectory of probability measures $\mu_{(t)}, 0 \leq t \leq T$ by $\mu$. We denote the set $\mathbf{H}_{2}[0, T]$ as all such trajectories for which

$$
\begin{gathered}
\|\mu\|_{2, T}^{2}:=\inf _{\vec{E}} \int_{0}^{T}\left|\frac{d \vec{E}_{(t)}}{d \mu_{(t)}}\right|^{2} \mu_{(t)}(d x) d t<\infty \\
\frac{\partial \mu}{\partial t}+\nabla_{x} \cdot \vec{E}_{(t)}=0
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in the sense of distributions. For a given pair of probability measures $\mu_{0}, \mu_{1}$, the extended action principle is defined by

$$
\begin{gathered}
\underline{A}\left(\mu_{0}, \mu_{1}\right):=\min _{\mu} \frac{1}{2}\|\mu\|_{2, T}^{2} \\
\mu_{(0)}=\mu_{0}, \mu_{(T)}=\mu_{1}
\end{gathered}
$$

The minimization problem is a special case of McCann interpolation

$$
\mu_{(t)}=\left[\frac{T-t}{T} \mathbf{I d}+\frac{t}{T} \mathbf{S}\right]_{\#} \mu_{0}
$$

where $\mathbf{S}$ is the map which realizes the optimal transportation of $\mu_{0}$ to $\mu_{1}$ under quadratic cost:

$$
\inf _{\mathbf{s}_{\#} \mu_{0}=\mu_{1}} \int_{\Omega}|x-\mathbf{S}(x)|^{2} \mu_{0}(d x)
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In case of discrete measure (D) The "Graph orbit" $\Gamma$ is a special case of admissible $\mu$ :

$$
\mu=\sum_{1}^{N} m_{i}(t) \delta_{x_{i}(t)}
$$

$$
\inf _{\Lambda} \sum_{1}^{N} \sum_{1}^{N} \Lambda_{i, j}\left|x_{i}-y_{j}\right|^{2}
$$

where $\sum_{i} \Lambda_{i, j}=m_{j}(T), \sum_{j} \Lambda_{i, j}=m_{i}(0)$.

## Extended action subjected to a prescribed pressure

 The extended Lagrangian with a pressure$$
A_{P}(\mu)=\frac{1}{2}\|\mu\|_{2}^{2}-\int_{0}^{T} P(x, t) \mu_{(t)}(d x) d t
$$

The associated Hamilton-Jacobi equation

$$
\frac{\partial \phi}{\partial t}+\frac{1}{2}\left|\nabla_{x} \phi\right|^{2}+P=0 \quad ; \quad(x, t) \in \Omega \times(0, T)
$$

and the continuity equation

$$
\frac{\partial \mu_{(t)}}{\partial t}+\nabla_{x} \cdot\left(\mu_{(t)} \nabla_{x} \phi\right)=0
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The end conditions:

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\mu_{(0)}=\mu_{0} \quad ; \quad \mu_{(T)}=\mu_{1}
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## Theorem

For any pair of end conditions $\mu_{0}, \mu_{1}$ there exists an orbit $\mu \in \mathbf{H}_{2}([0, T])$ which realizes the infimum of $A_{P}$.

## Some definitions

The cost function:

$$
\begin{align*}
C_{P}(x, y, \tau, t) & := \\
& \min \left\{\int_{\tau}^{t}\left(\frac{|\dot{\bar{x}}|^{2}}{2}+P(\bar{x}(s), s)\right) d s \quad ; \quad \bar{x}:[\tau, t] \rightarrow \Omega\right\} \tag{2}
\end{align*}
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where $\bar{x}(\tau)=y, \bar{x}(t)=x$.

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where $\bar{x}(\tau)=y, \bar{x}(t)=x$. In particular, if $P=0$ :

$$
C_{0}(x, y, \tau, t):=\frac{|x-y|^{2}}{2(t-\tau)}
$$

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i) A forward (res. backward) solution is defined, for

$$
\underline{t} \in[0, T], \text { by }
$$

$$
\bar{\phi}(x, t):=\min _{y}\left\{C_{P}(y, x, 0, t)+\phi(y, 0)\right\}, \text { res. }
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ii) If $\phi(\cdot, 0)$ and $\phi(\cdot, T)$ are Lipschitz on $\Omega$ then both $\bar{\phi}$ and $\phi$ are Lipschitz on $\Omega \times[0, T]$.
iii) $(\bar{\phi}, \underline{\phi})$ is called a reversible pair if $\bar{\phi}=\underline{\phi}$ on $\Omega$ for $t=0$ and $t=T$. In this case, $\bar{\phi}(x, t) \geq \underline{\phi}(x, t)$ on $\Omega \times[0, T]$.

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$(\bar{\phi}, \phi)$ is a reversible pair, then the reversibility set is defined by $K_{0}(\overline{\bar{\phi}}, \underline{\phi}):=\{(x, t) \in \Omega \times(0, T) ; \bar{\phi}(x, t)=\underline{\phi}(x, t):=\psi(x, t)\}$ $\nabla_{x} \psi(x, t)=\nabla_{x} \bar{\phi}=\nabla_{x} \underline{\phi}$ is Lipschitz on the reversibility set.
We call $\psi$ a reversible solution.

## Theorem

If $\phi_{0}, \phi_{1}$ maximizes $\int_{\Omega}\left(\phi_{1} \mu_{1}(d x)-\phi_{0} \mu_{0}(d x)\right)$ subjected
$\phi_{1}(x)-\phi_{0}(y) \leq C_{P}(x, y, 0, T)$ for any $x, y \in \Omega$, then $\left\{\phi_{0}, \phi_{1}\right\}$ is a reversible pair. The reversibility function $\psi$ verifies the Hamilton-Jacobi equation, and the optimal solution of $A_{P}$ is supported in $K_{0}\left(\phi_{0}, \phi_{1}\right)$ and verifies the continuity equation subjected $\nabla \phi=\nabla \psi$. Moreover, the flow

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\frac{d \mathbf{S}^{(t, s)}}{d t}=\nabla \psi\left(\mathbf{S}_{(x)}^{(t)}, t\right) \quad ; \quad \mathbf{T}^{(t, t)}:=\mathbf{I}_{\mathbf{d}}
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transports this orbit $\mathbf{S}_{\#}^{(\mathbf{t}, \mathbf{s})} \mu_{(\mathbf{s})}=\mu_{(\mathbf{t})}$.

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- The particles of the optimal flow subjected to a prescribed pressure do not collide (and, in particular, do not stick).
- There are no shock waves for the Hamilton-Jacobi equation. Indeed, $\psi$ is a reversible solution, as claimed.


## Implementation of the Inner energy

We now wish to extend the action principle to orbits composed of (Borel) measures in $\Omega$. Let $\overline{\mathcal{M}}$ be the set of such probability Borel measures. For any $\mu \in \overline{\mathcal{M}}$ set $\mu=\mu^{p p}+\tilde{\mu}$ to be its unique decomposition into its atomic and non-atomic parts. For each $\mu \in \overline{\mathcal{M}}$ we define the inner energy $\bar{\equiv}(\mu)$ as

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A \equiv(\mu ; T):=\frac{1}{2}\|\mu\|_{2, T}^{2}-\int_{0}^{T} \equiv\left(\mu_{(t)}\right) d t
$$

We now pose the following assumptions on $\xi$ :

$$
\xi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}, \quad \lim _{m \rightarrow 0} \frac{\xi(m)}{m}=0
$$

## Implementation of the Inner energy

We now wish to extend the action principle to orbits composed of (Borel) measures in $\Omega$. Let $\overline{\mathcal{M}}$ be the set of such probability Borel measures. For any $\mu \in \overline{\mathcal{M}}$ set $\mu=\mu^{p p}+\tilde{\mu}$ to be its unique decomposition into its atomic and non-atomic parts. For each $\mu \in \overline{\mathcal{M}}$ we define the inner energy $\bar{\Xi}(\mu)$ as

$$
\equiv(\mu):=\equiv\left(\mu^{p p}\right)=\sum_{x ; \mu(\{x\})>0} \xi(\mu(\{x\})) .
$$

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We now pose the following assumptions on $\xi$ :

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\xi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}, \quad \lim _{m \rightarrow 0} \frac{\xi(m)}{m}=0
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Remark: The assumption $\xi(m)=m^{\sigma}$ for $\sigma>1$ verifies verifies this condition.

Lemma
The action $A_{\equiv}(\cdot, T)$ is lower-semi-continues (I.s.c) with respect to $C\left([0, T] ; C^{*}(\Omega)\right)$.

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## Theorem

Given $\mu_{0}, \mu_{1} \in \overline{\mathcal{M}}$, there exists an action minimizer $\mu \in \mathbf{H}_{2}[0, T]$ for

$$
\underline{A}\left(\mu_{0}, \mu_{1} ; T\right):=\min _{\mu} A_{\equiv}(\mu, T)
$$

subjected to $\mu_{(0)}=\mu_{0} \quad, \quad \mu_{(T)}=\mu_{1}$

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We first consider a relaxation of the inner energy functional as follows:

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## Definition

Let $J: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$be a convex function satisfying $J(0)=J^{\prime}(0)=0$. Let $\theta \in C_{0}^{\infty}\left(\Omega ; \mathbb{R}^{+}\right)$such that $\theta(0)=1 \geq \theta(x)$ for all $x \in \Omega$. For each $\epsilon>0$, the inner energy function $\xi$ corresponding to $J$ is defined by

$$
\xi(m):=\int_{\Omega} J(m \theta(x)) d x ; m \geq 0 .
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Let $\theta_{\epsilon}(x):=\theta(x / \epsilon)$ and

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## Lemma

For each $\epsilon>0, \mu \rightarrow-\int_{0}^{T} \Xi_{\epsilon}\left(\mu_{(t)}\right) d t$ is continuous in the weak topology of $\mathbf{H}_{2}[0, T]$.

Let now

$$
A \equiv(\mu ; T)=\frac{1}{2}\|\mu\|_{2, T}^{2}-\int_{0}^{T} \Xi_{\epsilon}(\mu(t)) d t
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A_{\Xi}^{\epsilon}(\mu ; T)=\frac{1}{2}\|\mu\|_{2, T}^{2}-\int_{0}^{T} \Xi_{\epsilon}\left(\mu_{(t)}\right) d t
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Given $\mu_{0}, \mu_{1} \in \overline{\mathcal{M}}$, there exists an action minimizer for

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Let $\mu_{\epsilon}$ a minimizer of $A_{\Xi}^{\epsilon}$. Since the set $\mu_{\epsilon}, 0<\epsilon<1$, is pre-compact in $\mathbf{H}_{2}[0, T]$, we can look for a limit point of a subsequence of $\mu_{\epsilon}$ as $\epsilon \rightarrow 0$

## Consider now the pair of equations

$$
\begin{gathered}
\frac{\partial \mu}{\partial t}+\nabla \cdot\left(\mu \nabla_{x} \psi\right)=0 \\
\frac{\partial \psi}{\partial t}+\frac{1}{2}\left|\nabla_{x} \psi\right|^{2}-P_{\epsilon}=0
\end{gathered}
$$

where

$$
\begin{align*}
P_{\epsilon}(x, t)=-\bar{Z}_{\epsilon}^{\prime}(\mu(t))_{(x, t)} & := \\
& \epsilon^{-1} \int_{\Omega} J^{\prime}\left(\int_{\Omega} \theta_{\epsilon}(z-y) \mu_{(t)}(d z)\right) \theta_{\epsilon}(x-y) d y . \tag{3}
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$$

## Example

: if $\mu=\sum m_{i} \delta_{x_{i}}$ then

$$
P_{\epsilon}(x, t) \approx J^{\prime}\left(\sum_{j} m_{j} \theta\left(\frac{x_{j}-x}{\epsilon}\right)\right)
$$

Very strong and very short range repelling force!

## Theorem

If $\bar{\mu}^{(\epsilon)}$ is a maximizer of the action $A_{\equiv}^{\epsilon}$ then there exists a reversible-pair solution $\left(\bar{\phi}^{(\epsilon)}, \underline{\phi}\right)^{(\epsilon)}$ The reversibility set $K_{0}\left(\bar{\phi}^{(\epsilon)}, \underline{\phi}^{(\epsilon)}\right)$ contains the support of $\bar{\mu}^{(\epsilon)}$ in $\Omega \times(0, T)$. In addition, the reversibility set is invariant under the flow generated by the reversible solution

$$
\frac{d \mathbf{S}_{(\epsilon)}^{(s, t)}(x)}{d t}=\nabla \psi^{(\epsilon)}\left(\mathbf{S}_{(\epsilon)}^{(s, t)}(x), t\right) .
$$

As $\epsilon \rightarrow 0$, the particles' orbits $\mathbf{S}_{(\epsilon)}^{(s, t)}$ converge to a set-valued mapping $\mathbf{S}^{(s, t)}: \Omega \rightarrow \mathcal{B}(\Omega)$ so that $\lim _{\epsilon \rightarrow 0} \mathbf{S}_{(\epsilon)}^{(s, t)}(x) \in \mathbf{S}^{(s, t)}(x)$.

## Formal evolution equations in 1D

Suppose now an optimal transport is presented by the pair $\mu, \phi$ where

$$
\begin{align*}
& \mu_{(t)}(d x)=\rho(x, t) d x+\sum m_{i}(t) \delta_{x_{i}(t)} d x \\
& \int_{\Omega} \rho(x, t) d x+\sum m_{i}(t)=1 \tag{4}
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where $x_{i}(t)$ are smooth trajectories and $m_{i}(t)>0$ are smooth for $t \in[0, T]$.

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where $x_{i}(t)$ are smooth trajectories and $m_{i}(t)>0$ are smooth for $t \in[0, T]$.
The continuity equation takes the form

$$
\frac{\partial \rho}{\partial t}+\nabla_{x} \cdot\left(\rho \nabla_{x} \psi\right)+\sum \dot{m}_{i}(t) \delta_{x_{i}(t)}=0 .
$$

and the momentum equation

$$
\frac{\partial \psi}{\partial t}+\frac{1}{2}\left|\nabla_{x} \psi\right|^{2}+\sum \xi^{\prime}\left(m_{i}(t)\right) \mathbf{1}\left(x_{i}(t)-x\right)=0
$$

where $\mathbf{1}(x)=0$ if $x \neq 0, \mathbf{1}(1)=1$.

## Reversible solution in the limit $\epsilon=0$

The limit action function
$C(y, x, \tau, t ; \mu):=\inf _{\bar{x}}\left\{\int_{\tau}^{t}\left(\frac{1}{2}|\dot{\bar{x}}(s)|^{2}-\sum_{\mu_{(s)}(\{x\})>0} \xi^{\prime}\left(\mu_{(s)}(\{x\})\right) 1_{(\bar{x}(s), s)}\right) d s\right\}$
where the infimum is taken on the set of orbits $\bar{x}:[\tau, t] \rightarrow \Omega$ satisfying $\bar{x}(\tau)=y, \bar{x}(t)=x$.

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Fragmentation:

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\psi(x, t)=\inf _{y \in \Omega}\left[C(y, x, 0, t ; \mu)+\phi_{0}(y)\right] \leq \bar{\phi}(x, t):=\inf _{y \in \Omega}\left[\frac{|x-y|^{2}}{2 t}+\phi_{0}(y)\right]
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\end{equation*}
$$

Coagulation:

$$
\begin{align*}
& \underline{\phi}(x, t):= \\
& \sup _{y \in \Omega}\left[-\frac{|x-y|^{2}}{2(T-t)}+\phi_{1}(y)\right] \leq \sup _{y \in \Omega}\left[C(x, y, t, T ; \mu)+\phi_{1}(y)\right]=\psi(x, t) \tag{6}
\end{align*}
$$

## Representation of the solution

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\psi(x, t)=\psi_{0}(x, t)+\sum_{i} \alpha_{i}\left|x-x_{i}(t)\right| \quad, \quad \psi_{0} \in C^{1}
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\frac{\left|\alpha_{i}\right|^{2}(t)}{8}-\xi^{\prime}\left(m_{i}(t)\right)=0
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$$
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\text { Coagulation: } \frac{d m_{i}}{d t}=\bar{\rho}_{i}(t) \sqrt{8 \xi_{i}^{\prime}\left(m_{i}\right)} \\
\text { Fragmentation: } \quad \frac{d m_{i}}{d t}=-\bar{\rho}_{i}(t) \sqrt{8 \xi_{i}^{\prime}\left(m_{i}\right)},
\end{gathered}
$$

while the particle's orbit satisfies the Rankine-Hugoniot condition:

$$
\begin{align*}
\dot{x}_{i}=\frac{1}{2}\left[\psi_{x}\left(x_{i}^{+}(t), t\right)\right. & \left.+\psi_{x}\left(x_{i}^{-}(t), t\right)\right] \\
& :=\frac{\partial}{\partial x} \psi_{0}\left(x_{i}(t), t\right)+\sum_{j \neq i} \alpha_{j}(t) \frac{x_{i}(t)-x_{j}(t)}{\left|x_{i}(t)-x_{j}(t)\right|} \tag{7}
\end{align*}
$$



Figure: A representation of a reversible solution. Bold curves: particle orbits. Bold dots: observers positions at time $t$. Light curves: the characteristic curves for forward (res. backward) solution in the vicinity of type (I) (res. type (II)) orbit. Dashed light lines: the characteristic curves for forward (res. backward) solution in the vicinity of type (II) (res. type (I)) orbit.


Figure: Same as in Fig. ??, where the relaxation is emphasized in the magnifying lens.

